

\mathbb{N} **Natural numbers:** $\mathbb{N} = \{1, 2, 3, \dots\}$
 \mathbb{Z} **Integers:** $\mathbb{Z} = \{\dots, -3, -2, -1, 0, 1, 2, 3, \dots\}$
 \mathbb{Q} **Rational numbers:** $\mathbb{Q} = \{a/b \mid a, b \in \mathbb{Z}, b \neq 0\}$
 \mathbb{R} **Real numbers:** $\mathbb{R} = \{x \mid x \text{ is a real number}\}$
 \emptyset **Empty Set:** $\emptyset = \{\}$
 U **Universal set**

$x \in X$ **Set membership:** x is an element of X
 $x \notin X$ **Set non-membership:** x is not an element of X

$X = Y$ **Set equality:** every element of X is an element of Y and vice versa
 $X \subseteq Y$ and $Y \subseteq X$

$X \subseteq Y$ **Set inclusion:** every element of X is an element of Y ; X is a **subset** of Y
 $X \subseteq Y \Leftrightarrow \forall x, \text{ if } x \in X \text{ then } x \in Y$

$X \subset Y$ **Proper subset:** $X \subseteq Y$, but $X \neq Y$

$X \supseteq Y$

$X \supset Y$

$X \setminus Y$ **Set theoretic complement:** $\{x \mid x \in X \wedge x \notin Y\}$

$X \Leftrightarrow Y$ *iff*
 $X \Rightarrow Y$ *implies*

\forall *for all*
 \exists *there exists*
 \ni *such that*

$X \cap Y$ **Intersection:** $X \cap Y = \{x \in U \mid x \in X \wedge x \in Y\}$

$X \cup Y$ **Union:** $X \cup Y = \{x \in U \mid x \in X \vee x \in Y\}$

$\{a \mid \text{''statement about } a\}$ **Set comprehension:** the elements a which satisfy 'statement about a '.

big-O **Asymptotic upper bound** $f(n) = O(g(n)) \Leftrightarrow 0 \leq \lim_{x \rightarrow \infty} \left| \frac{f(x)}{g(x)} \right| < \infty$

little-o **Asymptotically negligible** $f(n) = o(g(n)) \Leftrightarrow \lim_{x \rightarrow \infty} \left| \frac{f(x)}{g(x)} \right| = 0$

\wedge **Logical AND**

\vee **Logical OR**

\oplus **Exclusive OR**

\square QED (quad erat demonstratum)

$$\hat{\mathbf{a}} = a_x \hat{\mathbf{x}} + a_y \hat{\mathbf{y}} + a_z \hat{\mathbf{z}}$$

Vector

$$\hat{\mathbf{a}} \cdot \hat{\mathbf{b}} = a_x b_x + a_y b_y + a_z b_z$$

Dot Product

$$\hat{\mathbf{a}} \times \hat{\mathbf{b}} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ a_x & a_y & a_z \\ b_x & b_y & b_z \end{vmatrix}$$

Cross Product

$$\nabla f(x, y, z) = \frac{\partial f}{\partial x} \hat{\mathbf{x}} + \frac{\partial f}{\partial y} \hat{\mathbf{y}} + \frac{\partial f}{\partial z} \hat{\mathbf{z}}$$

Gradient

$$\nabla \cdot \mathbf{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

Divergence

$$\nabla \times \mathbf{F} = \begin{vmatrix} \hat{\mathbf{x}} & \hat{\mathbf{y}} & \hat{\mathbf{z}} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix}$$

Curl

$$\nabla^2 f(x, y, z) = \frac{\partial^2 f}{\partial x^2} \hat{\mathbf{x}} + \frac{\partial^2 f}{\partial y^2} \hat{\mathbf{y}} + \frac{\partial^2 f}{\partial z^2} \hat{\mathbf{z}}$$

Laplacian

\leq \geq \ll \gg \sim \approx \neq ∞ ∞ Δ ∇ ∇^2

$$\prod_{n=0}^N f(n)$$

$$\sum_{n=0}^N f(n)$$

$$\int_a^b f(x)dx$$

$$\frac{dy}{dx}$$

$$\frac{dy}{dx}$$

$$\frac{\partial y}{\partial x}$$

$$\frac{\partial y}{\partial x}$$

$$\lim_{x \rightarrow a}$$

 \bullet \times

Greek Alphabet		
A	α	alpha
B	β	beta
Γ	γ	gamma
Δ	δ	delta
E	ϵ	epsilon
Z	ζ	zeta
H	η	eta
Θ	θ	theta
I	ι	iota
K	κ	kappa
Λ	λ	lambda
M	μ	mu
N	ν	nu
Ξ	ξ	xi
O	\omicron	omicron
Π	π	pi
P	ρ	rho
Σ	σ or ς	sigma
T	τ	tau
Y	υ	upsilon
Φ	φ or ϕ	phi
X	χ	chi
Ψ	ψ	psi
Ω	ω	omega

Matrices M X N (rows x columns)

One based indexing

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & \cdots & a_{1N} \\ a_{21} & a_{22} & \cdots & a_{2n} & \cdots & a_{2N} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & \cdots & a_{mN} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{M1} & a_{M2} & \cdots & a_{Mn} & \cdots & a_{MN} \end{bmatrix}$$

Zero based indexing

$$\begin{bmatrix} a_{00} & a_{01} & \cdots & a_{0n} & \cdots & a_{0(N-1)} \\ a_{10} & a_{11} & \cdots & a_{1n} & \cdots & a_{1(N-1)} \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ a_{m0} & a_{m1} & \cdots & a_{mn} & \cdots & a_{m(N-1)} \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ a_{(M-1)0} & a_{(M-1)1} & \cdots & a_{(M-1)n} & \cdots & a_{(M-1)(N-1)} \end{bmatrix}$$

Set Theory

Group

A group is a set G together with a binary operation \otimes which satisfy for all $x, y, z \in G$:

1. $(x \otimes y) \otimes z = x \otimes (y \otimes z)$ (associativity)
2. $\exists I \in G \ni I \otimes x = x \otimes I = x$ (identity)
3. $\exists x^{-1} \in G \ni x \otimes x^{-1} = x^{-1} \otimes x = I$ (inverse)
4. $x \otimes y \in G$ (closure – actually implied by “binary operation”)

Ring

A ring is a set R together with two binary operators \oplus and \otimes which satisfy for all $x, y, z \in R$:

1. under \oplus (Abelian group)
 - a. $(x \oplus y) \oplus z = x \oplus (y \oplus z)$ (associativity)
 - b. $\exists 0 \in R \ni 0 \oplus x = x \oplus 0 = x$ (identity)
 - c. $\exists -x \in R \ni x \oplus (-x) = (-x) \oplus x = 0$ (inverse)
 - d. $x \oplus y = y \oplus x$ (commutativity - Abelian)
2. under \otimes (semigroup)
 - a. $(x \otimes y) \otimes z = x \otimes (y \otimes z)$ (associativity)
3. \otimes distributes over \oplus (right and left)
$$x \otimes (y \oplus z) = (x \otimes y) \oplus (x \otimes z) \text{ and } (y \oplus z) \otimes x = (y \otimes x) \oplus (z \otimes x)$$

Field

A field is a set F together with two binary operators \oplus and \otimes which satisfy for all $x, y, z \in F$:

1. under \oplus (Abelian group)
 - a. $(x \oplus y) \oplus z = x \oplus (y \oplus z)$ (associativity)
 - b. $\exists 0 \in F \ni 0 \oplus x = x \oplus 0 = x$ (identity)
 - c. $\exists -x \in F \ni x \oplus (-x) = (-x) \oplus x = 0$ (inverse)
 - d. $x \oplus y = y \oplus x$ (commutativity - Abelian)
2. under \otimes (Abelian group except for zero restriction on inverse)
 - a. $(x \otimes y) \otimes z = x \otimes (y \otimes z)$ (associativity)
 - b. $\exists 1 \in F \ni 1 \otimes x = x \otimes 1 = x$ (identity)
 - c. $\forall x \neq 0 \exists x^{-1} \in F \ni x \otimes (x^{-1}) = (x^{-1}) \otimes x = 1$ (inverse)
 - d. $x \otimes y = y \otimes x$ (commutativity)
3. \otimes distributes over \oplus (right and left)
$$x \otimes (y \oplus z) = (x \otimes y) \oplus (x \otimes z) \text{ and } (y \oplus z) \otimes x = (y \otimes x) \oplus (z \otimes x)$$

Abelian Group

A group for which the elements commute.

Subgroup

A subset of a group which is closed under the group operation.

Semigroup

A semigroup is a set together with a binary operator in which the operation is associative.

(Note – need not have an identity element nor inverse).

Binary operation

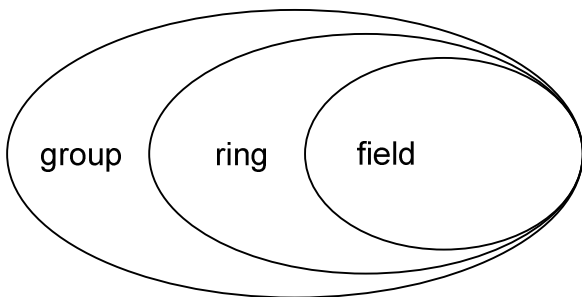
A binary operation on a nonempty set A is a map $f : A \times A \rightarrow A$ such that

1. f is defined for every pair of elements in A
2. f uniquely associates each pair of elements in A to some element of A

Closure

A mathematical structure A is said to be closed under an operation $+$ if, whenever a and b are both elements of A , then so is $a+b$.

Notes on set theory



Topology

Complete Metric Space

A **metric space** in which every **Cauchy sequence converges** (to an element in the space).

Examples include the real numbers with the usual metric, the complex numbers, finite-dimensional real and complex vector spaces, and the space of square-integrable functions on the unit interval $L^2([0,1])$.

Metric

A binary function $g(x, y)$ for a given set satisfying the following conditions:

1. $g(x, y) \geq 0$ (nonnegative)
1a. $g(x, y) = 0 \Leftrightarrow x = y$.
2. $g(x, y) = g(y, x)$ (symmetry)
3. $g(x, y) + g(y, z) \geq g(x, z)$ (triangle inequality)

A set possessing a metric is called a **metric space**.

Cauchy Sequence

A sequence a_1, a_2, \dots such that the metric $d(a_m, a_n)$ satisfies $\lim_{\min(m,n) \rightarrow \infty} d(a_m, a_n) = 0$.

Cauchy sequences in the rationals do not necessarily converge, but they do converge in the reals.

Convergent Sequence

A sequence S_n converges to the limit $\lim_{n \rightarrow \infty} S_n = S$ if, for any $\varepsilon > 0$, there exists an N such that $|S_n - S| < \varepsilon$ for all $n > N$. If S_n does not converge, it is said to diverge.

Every bounded monotonic sequence converges. Every unbounded sequence diverges.

Inner Product

An inner product is a generalization of the dot product. In a vector space, it is a way to multiply vectors together, with the result of this multiplication being a scalar.

More precisely, for a real vector space, and inner product $\langle \cdot, \cdot \rangle$ satisfies the following four properties. Let u, v and w be vectors and α be a scalar, then:

1. $\langle u + v, w \rangle = \langle u, w \rangle + \langle v, w \rangle$
2. $\langle \alpha v, w \rangle = \alpha \langle v, w \rangle$
3. $\langle v, w \rangle = \langle w, v \rangle$
4. $\langle v, v \rangle \geq 0$ and equal iff $v = 0$

A vector space together with an inner product on it is called an **inner product space**. This definition also applies to an **abstract vector space** over any field.

Examples of inner product spaces include:

1. The real numbers \mathbb{R} , where the inner product is given by $\langle x, y \rangle = xy$.
2. The Euclidean space \mathbb{R}^n , where the inner product is given by the dot product $\langle \mathbf{x}, \mathbf{y} \rangle = \sum_{i=1}^n x_i y_i$.
3. The vector space of real functions whose domain is a closed interval $[a, b]$ with the inner product

$$\langle f, g \rangle = \int_a^b f g \, dx$$

When given a complex vector space, the third property above is usually replaced by

$$\langle v, w \rangle = \overline{\langle w, v \rangle}$$

where \bar{z} refers to complex conjugation. With this property, the inner product is called a **Hermitian inner product** and a complex vector space with a Hermitian inner product is called a **Hermitian inner product space**.

Every inner product space is a metric space. The metric is given by $g(v, w) = \langle v - w, v - w \rangle$.

If this process results in a **complete metric space**, it is called a **Hilbert space**.

Complete Metric

A complete metric is a metric in which every Cauchy sequence is convergent. A topological space with a complete metric is called a complete metric space.

Inner Product Space

A **vector space** together with an **inner product** on it. If the inner product defines a **complete metric**, then the inner product space is called a **Hilbert space**.

Vector Space

A vector space V is a set that is closed under finite vector addition and scalar multiplication and the following conditions hold for all elements $\mathbf{x}, \mathbf{y}, \mathbf{z} \in V$ and any scalars $r, s \in F$:

1. Commutativity: $\mathbf{x} + \mathbf{y} = \mathbf{y} + \mathbf{x}$
2. Associativity of vector addition: $(\mathbf{x} + \mathbf{y}) + \mathbf{z} = \mathbf{x} + (\mathbf{y} + \mathbf{z})$
3. Additive identity $\forall \mathbf{x}: \mathbf{0} + \mathbf{x} = \mathbf{x} + \mathbf{0} = \mathbf{x}$
4. Existence of additive inverse: $\forall \mathbf{x} \exists -\mathbf{x} \ni \mathbf{x} + (-\mathbf{x}) = \mathbf{0}$
5. Associativity of scalar multiplication: $r(s\mathbf{x}) = (rs)\mathbf{x}$
6. Distributivity of scalar sums: $(r + s)\mathbf{x} = r\mathbf{x} + s\mathbf{x}$
7. Distributivity of vector sums: $r(\mathbf{x} + \mathbf{y}) = r\mathbf{x} + r\mathbf{y}$
8. Scalar multiplication identity: $1\mathbf{x} = \mathbf{x}$

The basic example is n -dimensional Euclidean space \mathbb{R}^n , where every element is represented by a list of n real numbers, scalars are real numbers, addition is componentwise, and scalar multiplication is multiplication on each term separately.

For a general vector space, the scalars are members of a field F , in which case V , is called a vector space over F .

Euclidean n -space \mathbb{R}^n is called a real vector space, and \mathbb{C}^n is called a complex vector space.

Norm

The norm of a mathematical object is a quantity that in some (possibly abstract) sense describes the length, size, or extent of the object.

Given a vector space V over K , a norm on a vector space V is a function $\|\cdot\|: V \rightarrow \mathbb{R}; x \rightarrow \|x\|$ with the following properties:

1. $\|\mathbf{v}\| \geq 0$, with equality iff $\mathbf{v} = \mathbf{0}$ (non-negative)
2. $\|a\mathbf{v}\| = |a|\|\mathbf{v}\|$ (multiplication by scalar)
3. $\|\mathbf{v} + \mathbf{u}\| \leq \|\mathbf{v}\| + \|\mathbf{u}\|$ (triangle inequality)

Most commonly “norm” refers to the vector norm

$$\|\mathbf{x}\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$

Hilbert Space

A Hilbert space is an inner product space that is complete with respect to the norm defined by the inner product.

A Hilbert space is always a Banach space, but the converse need not hold.

Banach Space

A Banach space is a complete vector space B with a norm $\|\cdot\|$. Two norms $\|\cdot\|_{(1)}$ and $\|\cdot\|_{(2)}$ are called equivalent if they give the same topology, which is equivalent to the existence of constants c and C such that

$$\|v\|_{(1)} \leq c \|v\|_{(2)} \quad \text{and} \quad \|v\|_{(2)} \leq C \|v\|_{(1)}$$

hold for all v .

In the finite-dimensional case, all norms are equivalent. An infinite-dimensional space can have many different norms.

A basic example is n -dimensional Euclidean space with the Euclidean norm. Usually the notion of Banach space is only used in the infinite dimensional setting, typically as a vector space of functions. For example, the set of continuous functions on the real line with the norm of a function f given by

$$\|f\| = \sup_{x \in \mathbb{R}} |f(x)|$$

is a Banach space.

On the other hand, the set of continuous functions on the unit interval $[0,1]$ with the norm of a function f given by

$$\|f\| = \int_0^1 |f(x)| dx$$

is not a Banach space, because it is not complete. For instance, the Cauchy sequence of functions

$$f_n = \begin{cases} 1 & \text{for } x \leq \frac{1}{2} \\ \frac{1}{2}n + 1 - nx & \text{for } x \leq \frac{1}{2} + \frac{1}{n} \\ 0 & \text{for } x > \frac{1}{2} + \frac{1}{n} \end{cases}$$

does not converge to a continuous function.

Hilbert spaces with their norm given by the inner product are examples of Banach spaces. While a Hilbert space is always a Banach space, the converse need not hold. Therefore, it is possible for a Banach space not to have a norm given by an inner product. For instance, the supremum norm cannot be given by an inner product.

Vector norms defined for a complex vector $\mathbf{x} = [x_1 \ x_2 \ \dots \ x_n]^T$ ($|x_k|$ denotes the complex modulus)

l^1 -norm

$$|\mathbf{x}|_1 = \sqrt{\sum_{k=1}^n |x_k|}$$

l^2 -norm

$$|\mathbf{x}|_2 = \sqrt{\sum_{k=1}^n |x_k|^2}$$

l^p -norm

$$|\mathbf{x}|_p = \sqrt[p]{\sum_{k=1}^n |x_k|^p}$$

l^∞ -norm

$$|\mathbf{x}|_\infty = \max_i |x_i|$$

Function norms

L^2 -norm

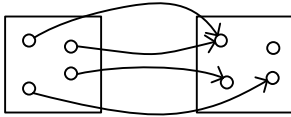
Applied to a function $y(x)$: $|y|^2 \equiv \langle y | y \rangle \equiv \int |y(x)|^2 dx$, where $\langle f | g \rangle$ denotes the angle bracket.

Mappings

Morphism/map

A way of associating unique objects to every point in a given set. A morphism $f : A \rightarrow B$ from A to B is a function f such that for every $a \in A$, there is a unique object $f(a) \in B$.

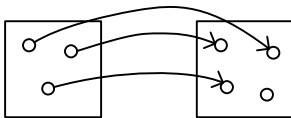
$$f : A \rightarrow B \Rightarrow \forall a \in A \exists \text{ a unique } f(a) \in B \quad \text{(morphism/map)}$$



Injection/One-to-one

A mapping $f(x)$ such that whenever $f(x) = f(y)$, it must be the case that $x = y$. In other words a mapping is an injection if it maps distinct objects to distinct objects.

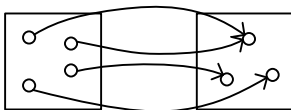
$$f : A \rightarrow B \mid f(x) = f(y) \Rightarrow x = y \quad \text{(injection/one-to-one)}$$



Surjection/onto

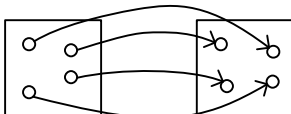
A mapping $f(x)$ such that for any $b \in B$, there exists an $a \in A$ for which $b = f(a)$.

$$f : A \rightarrow B \mid \forall b \in B \exists a \in A \ni b = f(a) \quad \text{(surjection/onto)}$$



Bijection /Isomorphism

A mapping $f(x)$ which is **one-to-one** and **onto**.



Note – bijections have inverses.

Homeomorphic

Continuous, one-to-one, onto, and having a continuous inverse.

Discrete Fourier Transform

$$f_k = \frac{1}{N} \sum_{n=0}^{N-1} F_n e^{2\pi i kn/N}$$

$$F_n = \sum_{k=0}^{N-1} f_k e^{-2\pi i kn/N}$$

Fourier Series

$$f(x) = \frac{1}{2} a_0 + \sum_{n=1}^{\infty} a_n \cos\left(\frac{2\pi nx}{L}\right) + \sum_{n=1}^{\infty} b_n \sin\left(\frac{2\pi nx}{L}\right)$$

$$a_0 = \frac{2}{L} \int_{-L/2}^{L/2} f(x) dx$$

$$a_n = \frac{2}{L} \int_{-L/2}^{L/2} f(x) \cos\left(\frac{2\pi nx}{L}\right) dx$$

$$b_n = \frac{2}{L} \int_{-L/2}^{L/2} f(x) \sin\left(\frac{2\pi nx}{L}\right) dx$$

or

$$f(x) = \sum_{n=-\infty}^{\infty} A_n e^{i(2\pi nx/L)}$$

$$A_n = \frac{1}{L} \int_{-L/2}^{L/2} f(x) e^{-i(2\pi nx/L)} dx$$

Fourier Transform

$$h(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} H(\omega) e^{i\omega t} d\omega$$

$$H(\omega) = \int_{-\infty}^{\infty} h(t) e^{-i\omega t} dt$$

Laplace Transform

$$f(t) = \frac{1}{i2\pi} \int_{c-j\infty}^{c+j\infty} e^{st} H(s) ds$$

$$H(s) = \int_0^{\infty} f(t) e^{-st} dt$$

z-Transform

$$x[n] = \oint_C X(z) z^{n-1} dz$$

$$X(z) = \sum_{n=0}^{\infty} x[n] z^{-n}$$

Trigonometry

$$\sin \alpha = \frac{\text{opp}}{\text{hyp}}$$

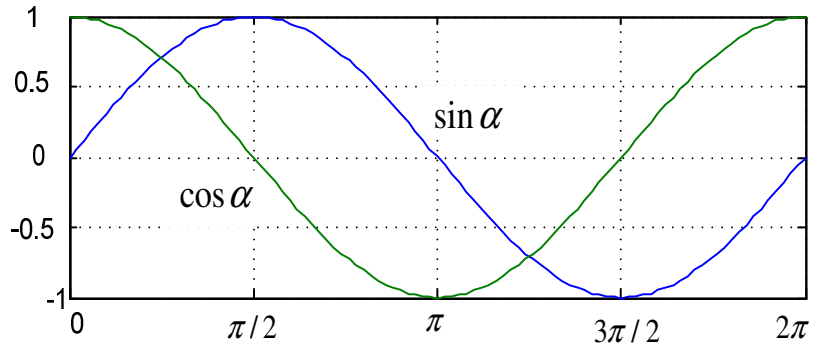
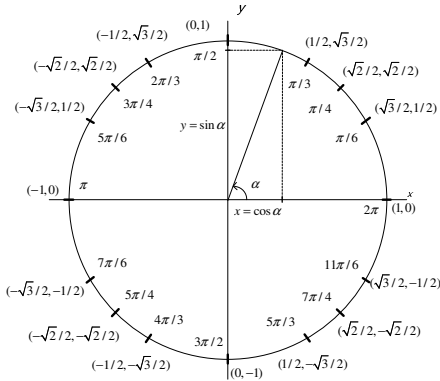
$$\cos \alpha = \frac{\text{adj}}{\text{hyp}}$$

$$\tan \alpha = \frac{\text{adj}}{\text{opp}} = \frac{\sin \alpha}{\cos \alpha}$$

$$\csc \alpha = \frac{\text{hyp}}{\text{opp}} = \frac{1}{\sin \alpha}$$

$$\sec \alpha = \frac{\text{hyp}}{\text{adj}} = \frac{1}{\cos \alpha}$$

$$\cot \alpha = \frac{\text{opp}}{\text{adj}} = \frac{\cos \alpha}{\sin \alpha} = \frac{1}{\tan \alpha}$$



Law of cosines

$$c^2 = a^2 + b^2 - 2ab \cos(C)$$

Law of sines

$$\frac{\sin a}{A} = \frac{\sin b}{B} = \frac{\sin c}{C}$$

Taylor's Series Expansion

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n+1}}{(2n+1)!}$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots = \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!}$$

Identities

$$\sin(\alpha + \beta) = \sin \alpha \cos \beta + \cos \alpha \sin \beta$$

$$\sin(\alpha - \beta) = \sin \alpha \cos \beta - \cos \alpha \sin \beta$$

$$\cos(\alpha + \beta) = \cos \alpha \cos \beta - \sin \alpha \sin \beta$$

$$\cos(\alpha - \beta) = \cos \alpha \cos \beta + \sin \alpha \sin \beta$$

$$\sin(2\alpha) = 2 \sin \alpha \cos \alpha$$

$$\cos(2\alpha) = \cos^2 \alpha - \sin^2 \alpha$$

$$\sin \alpha + \sin \beta = 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

$$\sin \alpha - \sin \beta = 2 \cos \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2}$$

$$\cos \alpha + \cos \beta = 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

$$\cos \alpha - \cos \beta = -2 \sin \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2}$$

$$\tan \alpha + \tan \beta = \frac{\sin(\alpha + \beta)}{\cos \alpha \cos \beta}$$

$$\tan \alpha - \tan \beta = \frac{\sin(\alpha - \beta)}{\cos \alpha \cos \beta}$$

$$\cot \alpha + \cot \beta = \frac{\sin(\alpha + \beta)}{\sin \alpha \sin \beta}$$

$$\cot \alpha - \cot \beta = \frac{-\sin(\alpha - \beta)}{\sin \alpha \sin \beta}$$

Euler's formula

$$e^{i\alpha} = \cos \alpha + i \sin \alpha$$

Derivative

$$f'(x) = \frac{df(x)}{dx} = \lim_{\delta x \rightarrow 0} \frac{f(x + \delta x) - f(x)}{\delta x}$$

Integral

Fundamental Theorem of Calculus

$$\int_a^b f(x) dx = F(b) - F(a) \quad \text{where } F'(x) = f(x)$$

Integration by Parts

$$\int_a^b f(x)g'(x)dx = f(x)g(x)\Big|_a^b - \int_a^b g(x)f'(x)dx \quad \text{or } \int u dv = uv - \int v du$$

Substitution Rule

$$\int_{\phi(a)}^{\phi(b)} f(x)dx = \int_a^b f(\phi(t))\phi'(t)dt$$

Common Derivatives

$$\frac{d}{dx} cx = c$$

$$\frac{d}{dx} x^n = nx^{n-1}$$

$$\frac{d}{dx} e^x = e^x$$

$$\frac{d}{dx} \ln x = \frac{1}{x}$$

$$\frac{d}{dx} \sin x = \cos x$$

$$\frac{d}{dx} \cos x = -\sin x$$

$$\frac{d}{dx} [f + g] = \frac{df}{dx} + \frac{dg}{dx}$$

$$\frac{d}{dx} [fg] = f \frac{dg}{dx} + \frac{df}{dx} g$$

$$\frac{d}{dx} \frac{f}{g} = \frac{\frac{df}{dx} g - f \frac{dg}{dx}}{g^2}$$

$$\frac{dy}{dx} = \frac{dy}{du} \frac{du}{dx}$$

Common Integrals

$$\int dx = x + C$$

$$\int cf(x)dx = c \int f(x)dx$$

$$\int [f(x) + g(x)]dx = \int f(x)dx + \int g(x)dx$$

$$\int x^n dx = \frac{x^{n+1}}{n+1} + C$$

$$\int \frac{1}{x} dx = \ln |x| + C$$

$$\int \frac{1}{1+x^2} dx = \arctan x + C$$

$$\int \ln x dx = x \ln x - x + C$$

$$\int e^x dx = e^x + C$$

$$\int a^x dx = \frac{a^x}{\ln a} + C$$

$$\int \sin x dx = -\cos x + C$$

$$\int \cos x dx = \sin x + C$$